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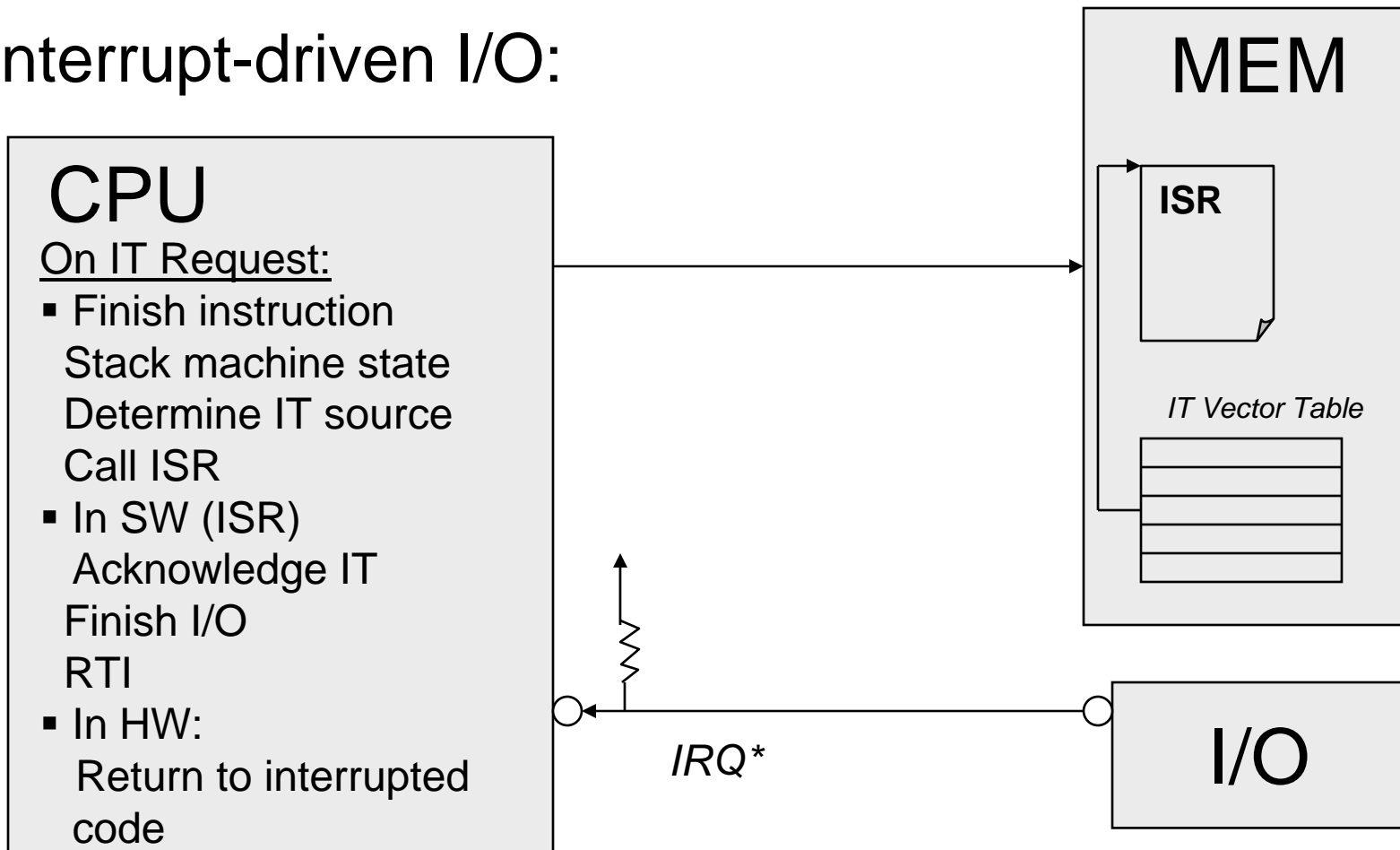
# EECE 276

# Embedded Systems

Interrupts: Basics  
Shared data problem  
Latency

# Recap: IT Technique

## Interrupt-driven I/O:



# IT Technique: Key points

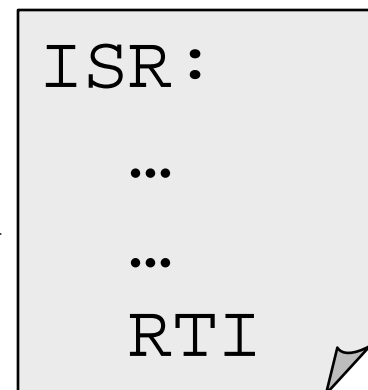
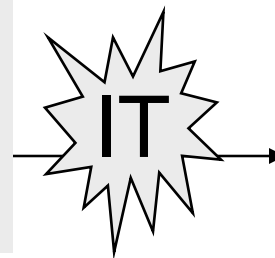
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- IT is always generated by a special event
  - HW (mostly), SW (sometime)
- If enabled, an IT can be serviced between **any** two instructions
  - Instructions are always *fully* executed

**NOTE: C statements often mean multiple instructions**

```
void foo(int i) {  
    int j;  
    j = i + 123;  
    ...  
}
```

```
LDAA  $8 , X  
ADDA  #123  
STAA  $6 , X
```



# IT Technique: Key points

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- All registers must be saved/restored at the beginning/end of the ISR
  - Saving/restoring the *context* (a.k.a. *context switch*)
- Locating the ISR: IT vector table
- Multiple, simultaneous IT-s: priority scheme
  - HC11/12: fixed scheme on internals, single external source
  - Others: IT priority controller (extra HW)
- Interrupting the ISR: IT nesting
  - HC11/12: Upon entry to an ISR, IT-s are disabled
  - Others: Higher priority IT-s are enabled

# Shared Data Problem

- Code monitors two temperatures
- Temperatures must be equal
- If not -> ALARM
- vReadTemps() is the ISR, called periodically

## Behavior:

The code occasionally sets off the ALARM, even if everything seems normal. ???

```
static int iTemps[2];
void interrupt vReadTemps() {
    iTemps[0] = // read in value from HW;
    iTemps[1] = // read in value from HW;
}
void main(void) {
    int iTemp0, iTemp1;
    while (TRUE) {
        iTemp0 = iTemps[0];
        iTemp1 = iTemps[1];
        if (iTemp0 != iTemp1) {
            // Set off ALARM
        }
    }
}
```

# Shared Data Problem

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Sequence of events:

1. main: `iTemp0 = iTemps[0];`
2. ISR: updates `iTemps[0]` and `iTemps[1]`
3. main: `iTemp1 = iTemps[1];`
4. main: `iTemp0 != iTemp1` → ALARM!

Alternative main(): →

*Does it fix the problem? NO!*

**IT always comes at the wrong time.**

```
....  
void main(void) {  
  while (TRUE) {  
    if (iTemps[0] != iTemps[1]) {  
      // Set off ALARM  
    }  
  }  
}
```

# Shared Data Problem

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Source of the problem:

iTemps[] array is shared between the main() and the ISR. If IT happens while main() is using the array -> the data may be in an inconsistent state.

Solving the problem:

Enable/disable ITs

*Atomic/critical section* →

```
...
void main(void) {
    int iTemp0, iTemp1;
    while (TRUE) {
        disableIT();
        iTemp0 = iTemps[0];
        iTemp1 = iTemps[1];
        enableIT();
        if (iTemp0 != iTemp1) {
            // Set off ALARM
        }
    }
    ...
}
```

# Interrupt latency

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How fast will a system react to interrupts? Depends on:

1. Max. time while IT-s are disabled.
2. Max. time taken to execute higher priority IT-s.
3. Time taken by ISR invocation (context save, etc.) and return (context restore)
4. “Work” time in ISR to generate a response.

Values:

For 3: see processor docs.

Others: count instructions – does not work well for processors with cache!

General rule: **WRITE SHORT IT SERVICE ROUTINES!**

# Interrupt latency: Disabling Interrupts

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Example system:

- Must disable IT-s for 125uS to process pressure variables.
- Must disable IT-s for 250uS to manage timer
- Must respond to a network IT within 600uS, the network ISR takes 300uS to execute.

Will it work?

# Interrupt latency: Disabling Interrupts

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Will it work? Yes, as the longest time IT-s are disabled is 250uS and 300uS is required for the network ISR.  $WCRT = 550uS < 600 uS$ .

Will it work with a processor of half the speed?

No!

$$WCRT = 500uS + 600uS = 1100uS > 600uS$$

# Alternative to disabling IT-s

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```
int iTempAs[2];
int iTempBs[2];
bool fUsingB = FALSE;
void interrupt vReadTemps() {
    if(fUsingB) {
        iTempAs[0] = // read from HW
        iTempAs[1] = // read from HW
    } else {
        iTempBs[0] = // read from HW
        iTempBs[1] = // read from HW
    }
}
```

*Two sets of  
variables*

*One flag to control  
which set is used*

# Alternative to disabling IT-s

---

```
void main () {
    while (TRUE) {
        if(fUsingB) {
            if (iTempBs[0] != iTempBs[1]) {
                // set off ALARM
            }
        } else {
            if (iTempAs[0] != iTempAs[1]) {
                // set off ALARM
            }
        }
        fUsingB = !fUsingB;
    }
}
```

Assumption:

*Changing the flag  
is an atomic  
operation!*